



Visual Enhancement Using Sparsity-Based Image Decomposition for Low Backlight Displays

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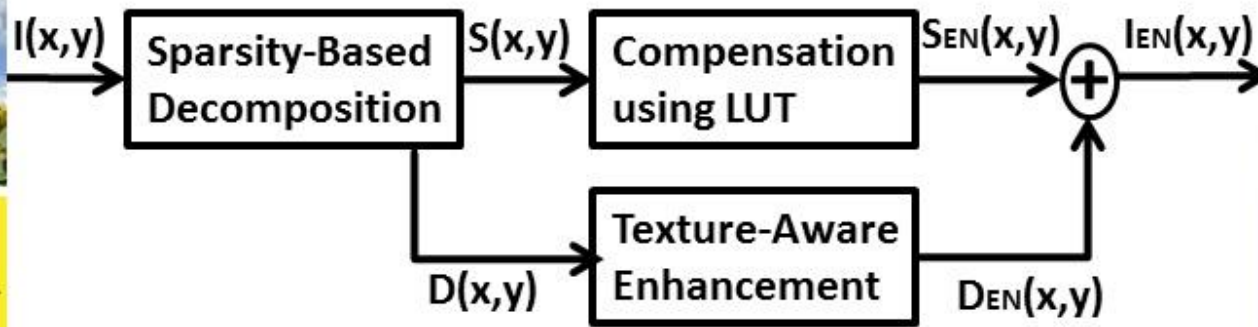
Our proposed system:

scale down the backlight, enhance the image, save power.

Input



Full Backlight



Enhanced



Low Backlight

Image-Backlight Relationship

- To perceive a pixel on the display, we can model as

$$L = B \cdot t(x, y) + O(x, y) = b \cdot B_{MAX} \cdot \left(\frac{I(x, y)}{V}\right)^\Gamma + o\{I(x, y)\}$$

- L: Luminance
- B: Backlight
- $t(x, y)$: transmittance
- $O(x, y)$: Luminance offset

- To perceive the same L ,

$$\begin{aligned} L &= 1 \cdot B_{MAX} \cdot \left(\frac{I_F(x, y)}{V}\right)^\Gamma + o_F(x, y) \\ &= b \cdot B_{MAX} \cdot \left(\frac{I_C(x, y)}{V}\right)^\Gamma + o_C(x, y) \end{aligned}$$

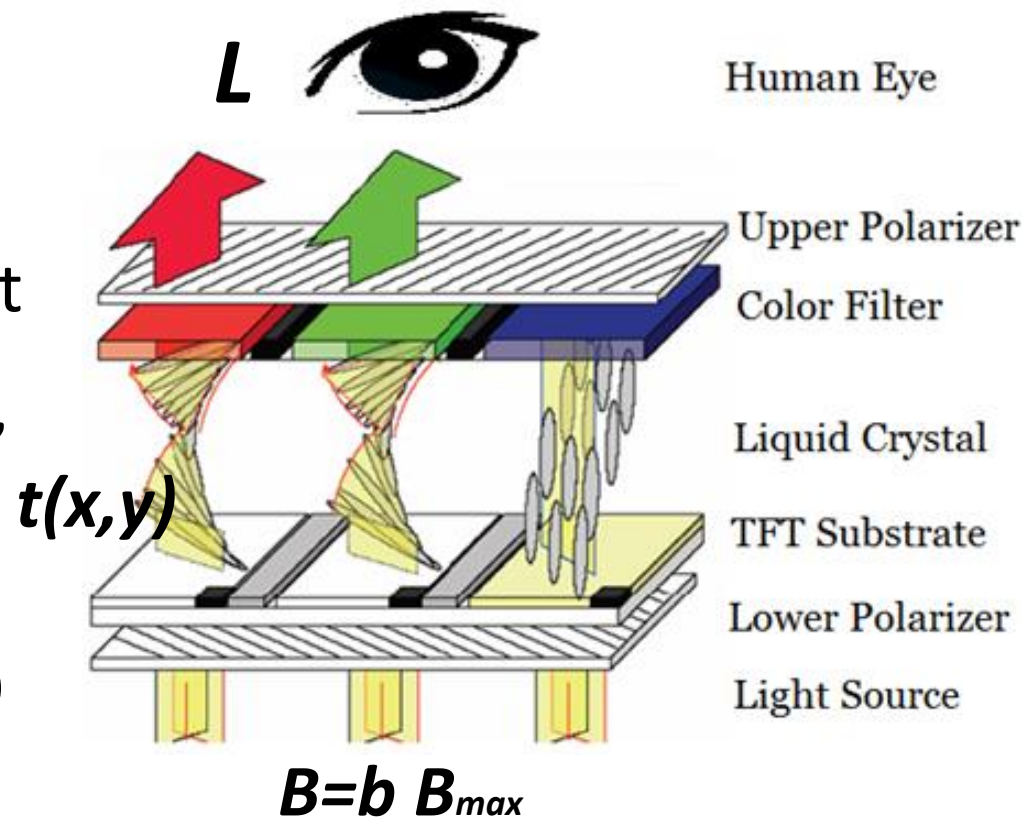


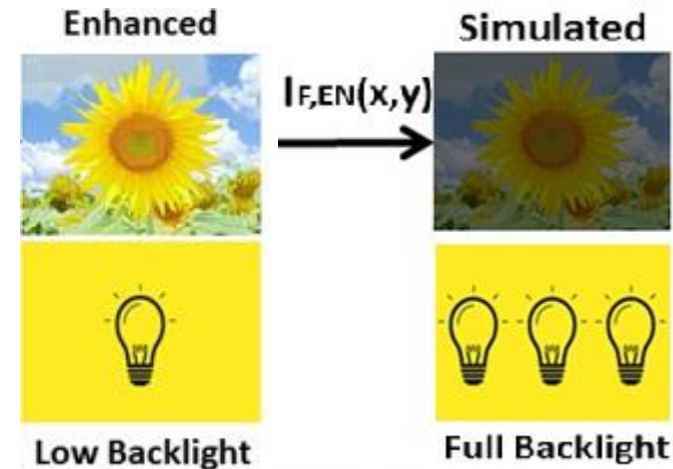
Image-Backlight Relationship

- We can simulate
 - the compensated image on low backlight
 - by scaling-down the enhanced image on full backlight
- The scale-down factor = $b^{\frac{1}{\Gamma}}$

$$I_F(x, y) = V \cdot \left[b \cdot \left(\frac{I_C(x, y)}{V} \right)^\Gamma + \frac{o_C(x, y) - o_F(x, y)}{B_{MAX}} \right]^\frac{1}{\Gamma}$$

$$L = b \cdot B_{MAX} \cdot \left(\frac{I_C(x, y)}{V} \right)^\Gamma = B_{MAX} (b^{\frac{1}{\Gamma}} \cdot I_C(x, y))^\Gamma$$

$$I_F(x, y) = 1 \cdot \left[b \cdot \left(\frac{I_C(x, y)}{1} \right)^\Gamma + 0 \right]^\frac{1}{\Gamma} = b^{\frac{1}{\Gamma}} \cdot I_C(x, y)$$



Sparsity-Base Image Decomposition for Enhancement



$$I = S + D$$

- To enhance an image, we can firstly decompose an image into a base layer (**S**) and a detail layer (**D**).
- We proposed a general form of sparsity-base decomposition:

$$\min_S \alpha \cdot \int_{\Omega} \|S - I\|^2 + (1 - \alpha) \int_{\Omega} \|S - I\| + \eta \cdot \int_{\Omega} \|\partial S\|^2 + \lambda \cdot \int_{\Omega} \|\partial S\|_0$$

Solvers

Let's discretize it and solve **S** alternatively :

$$\min_{S,v,w} \alpha \cdot \sum_{(x,y)} \|S - I\|^2 + (1-\alpha) \cdot \gamma \cdot \sum_{(x,y)} \|S - I - v\|^2 + (1-\alpha) \cdot \sum_{(x,y)} \|v\|$$

$$+ \eta \cdot \sum_{(x,y)} \|\partial S\|^2 + \beta \cdot \sum_{(x,y)} \|\partial S - w\|^2 + \lambda \cdot \sum_{(x,y)} \|w\|_0$$

To solve **S**,

$$S = F^{-1} \left\{ \frac{(\alpha + \gamma - \alpha\gamma)F(I) + (\gamma - \gamma\alpha)F(v) + \beta F^*(\partial)F(w)}{(\alpha + \gamma - \alpha\gamma) + (\eta + \beta)F^*(\partial)F(\partial)} \right\}$$

To solve **v**,

$$v = \max \left\{ \left| S - I \right| - \frac{1}{\alpha}, 0 \right\} \cdot \frac{S - I}{|S - I|}$$

To solve **w**,

$$w = \max_w \sum_{(x,y)} \|\partial S - w\|^2 + \frac{\lambda}{\beta} \cdot C(x, y)$$

$$C(x, y) = \sum_{(x,y)} |w_x(x, y)| + |w_y(x, y)|$$

$$\text{where } |w_x(x, y)| + |w_y(x, y)| = 1$$

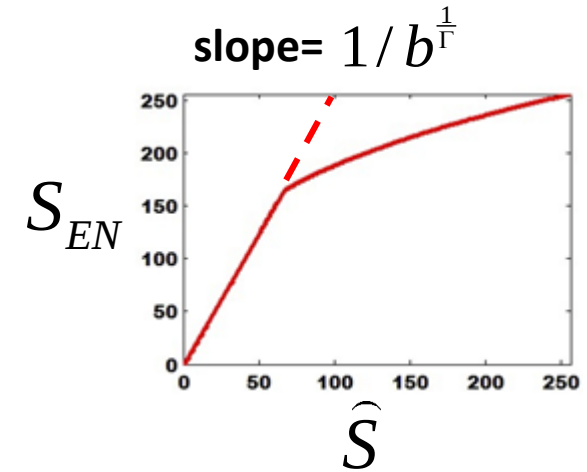
$$\text{if } M(x, y) \cdot (|\partial_x S(x, y)|^2 + |\partial_y S(x, y)|^2) \leq \xi$$

**L₀ Norm
of
Gradient**

Base Compensation & Detail Enhancement

- We compensate the base layer:

- Using a look-up table $S_{EN} = V \cdot LUT(\frac{\hat{S}}{V})$
- L2-distance between
 - the line with the slope $1/b^{\frac{1}{\Gamma}}$
 - gamma correction



- We can enhance the detail layer.

- Detail: $\hat{D} = I - \hat{S}$

- Enhance: $D_{EN} = g \cdot \hat{D} \cdot \left(\frac{V + JND(V)}{V}\right)^\tau$

$$\tau = \frac{T - T_{\min}}{T_{\max} - T_{\min}} + 1$$

- Final Intensity: $I_{EN} = S_{EN} + D_{EN}$



$$T = \frac{WTV_x^2}{WIV_x^2 + \varepsilon} + \frac{WTV_y^2}{WIV_y^2 + \varepsilon}$$

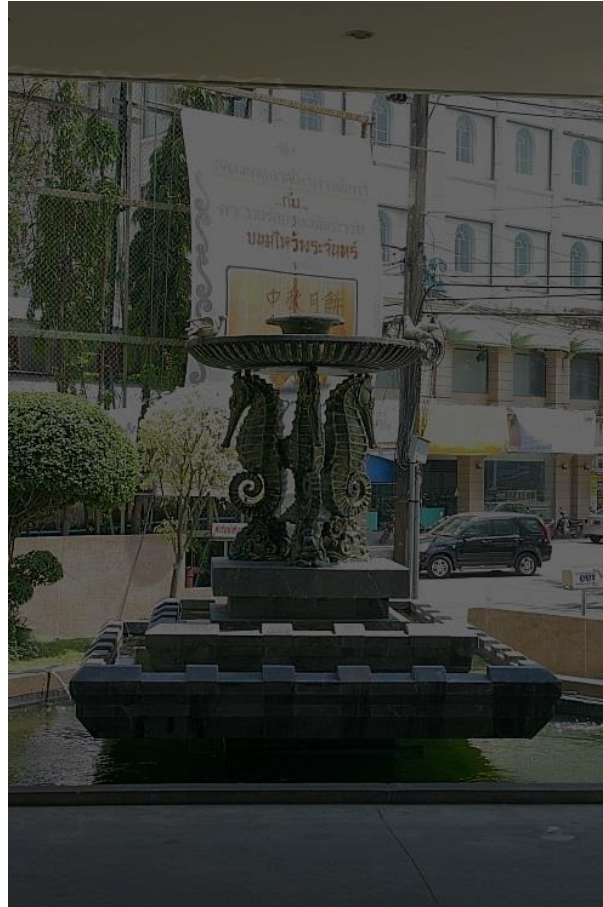
$$WTV_i = \sum_{(x,y) \in W} |\partial_i \hat{D}|$$

$$WIV_i = \left| \sum_{(x,y) \in W} \partial_i \hat{D} \right|$$

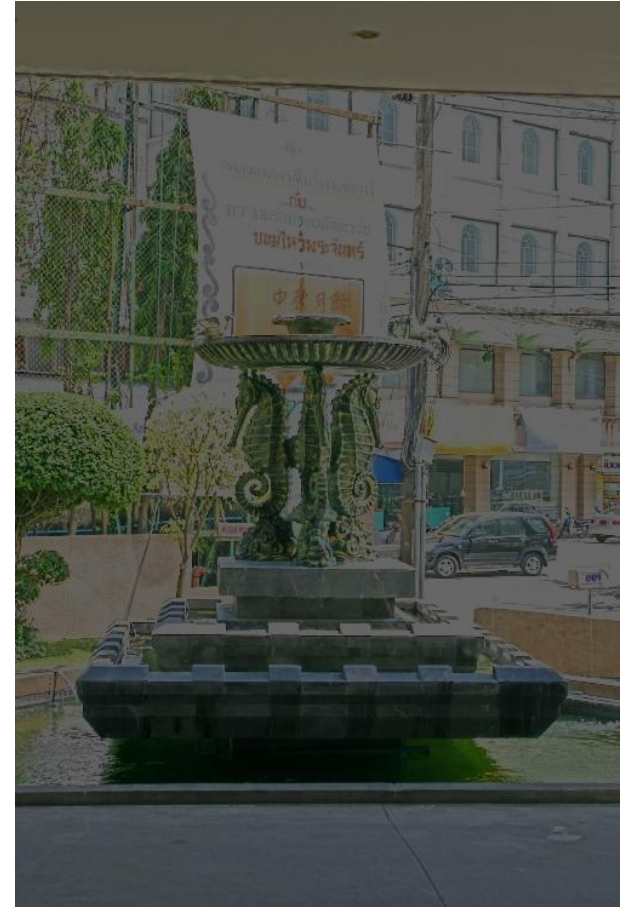
Simulated Results



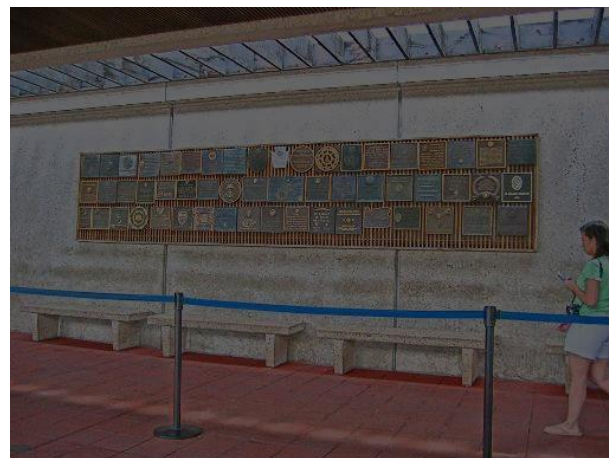
Original
simulation for 100% Backlight



Tsai et al.
simulation for 13.3% Backlight



Ours
simulation for 13.3% Backlight



Original
simulation for 100% Backlight

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